



*This project receives funding
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Horizon 2020 research and
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SECoP and Metadata for Sample Environment

Klaus Kiefer (HZB) Workshop on Research Data Management, Berlin, 11 June 2019

- **Sample Environment**
- **Definition of the problem**
- **SECoP**
- **Metadata**
- **Implementations**
- **What still needs to be done...**

Sample Environment

VEKMAG: 9T 3D-Vector Magnet und ^4He Cryostat @ PM2

F. Radu, H. Ryll, W. Kuch, H. Zabel, C. Back

B. Klemke, K. Kiefer



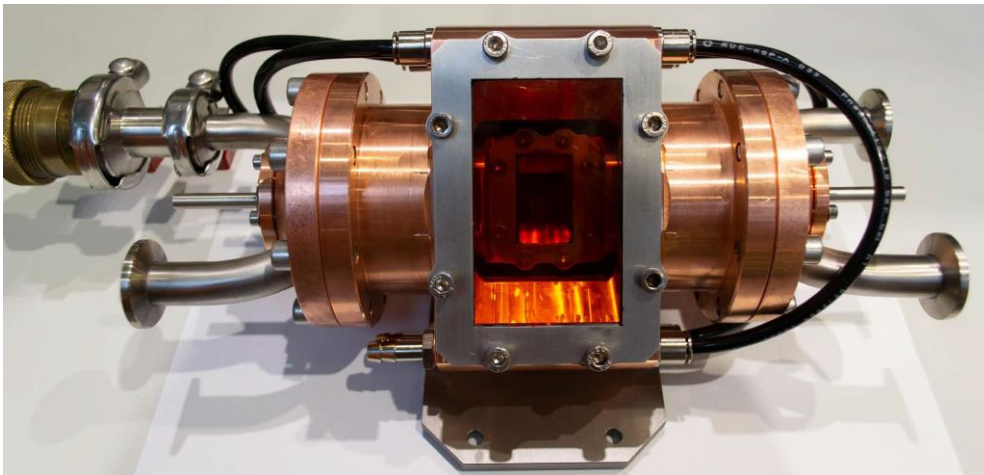
Physical properties:

- **Temperature (2 K .. 500 K)**
- **Magnetic field (9T, 2T, 1T)**
- Helium level



HOT VAPOR ADSORPTION CHAMBER FOR X-RAY DIFFRACTION @ KMC-2

R. Blažević, N. Grimm, D. Wallacher, D. Többens, S. Kaskel, I. Senkovska and V. Bon



Physical properties:

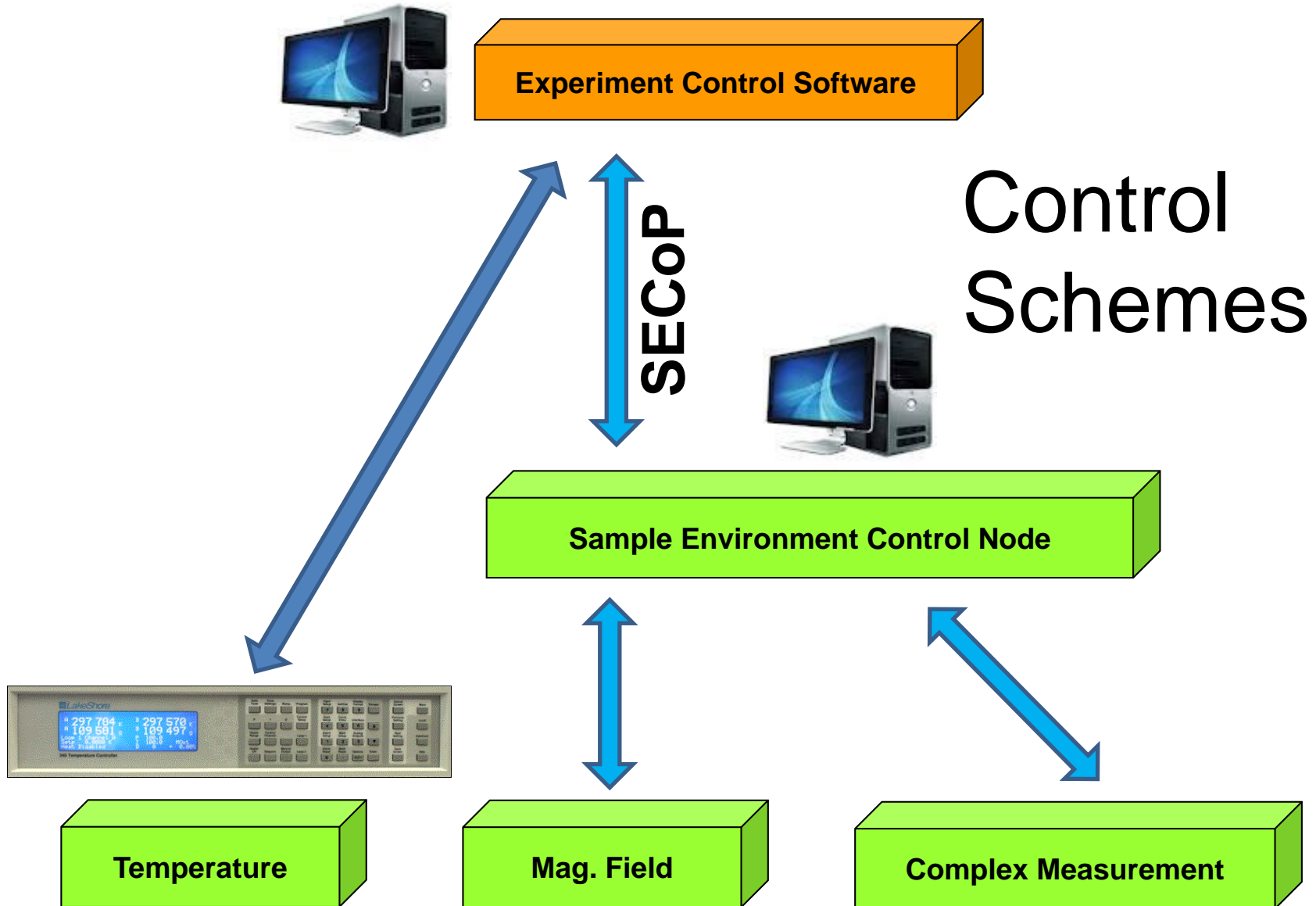
- Temperature (293 K to 423 K)
- Pressure (up to 5 bar)

Definition of the Problem

Problems:

- **Different** Experiment Control **Softwares** (Caress, NICOS, spec, LISE/M...) with different ways to control SE
- **Complex** SE software interface **protocols** (CORBA, TACO/TANGO, EPICS...)
- **Time consuming integration** of new or external SE equipment
- **No easy mobility** of sample environment equipment
- **No standard for SE metadata**

- **Physicists** are programming drivers



- **Common** Standard
- **Inclusive** (fulfilling the needs of all facilities, no hard restrictions for hardware/software)
- **Simple** (easy to use and to implement)
- **Self explaining** (possibility for plug and play operation with compatible clients)
- Integration of **Metadata** (self explaining)

**simple, inclusive, self explaining,
provides metadata**



www.sampleenvironment.org

The International Society for Sample Environment

Committee for the Standardization of Sample Environment Communication

(Head: M. Zolliker (PSI), Members: K. Kiefer (HZB), E. Faulhaber (MLZ), A. Pettersson (ESS), Alan Ye (NIST),
Facility contacts: E. Lelièvre-Berna (ILL), K. Baker (STFC), Andrew Manning (ANSTO), Gary Lynn (SNS),
Koji Kaneko (JRR-3), Seiko Kawamura (J-Parc))



Task 7.1



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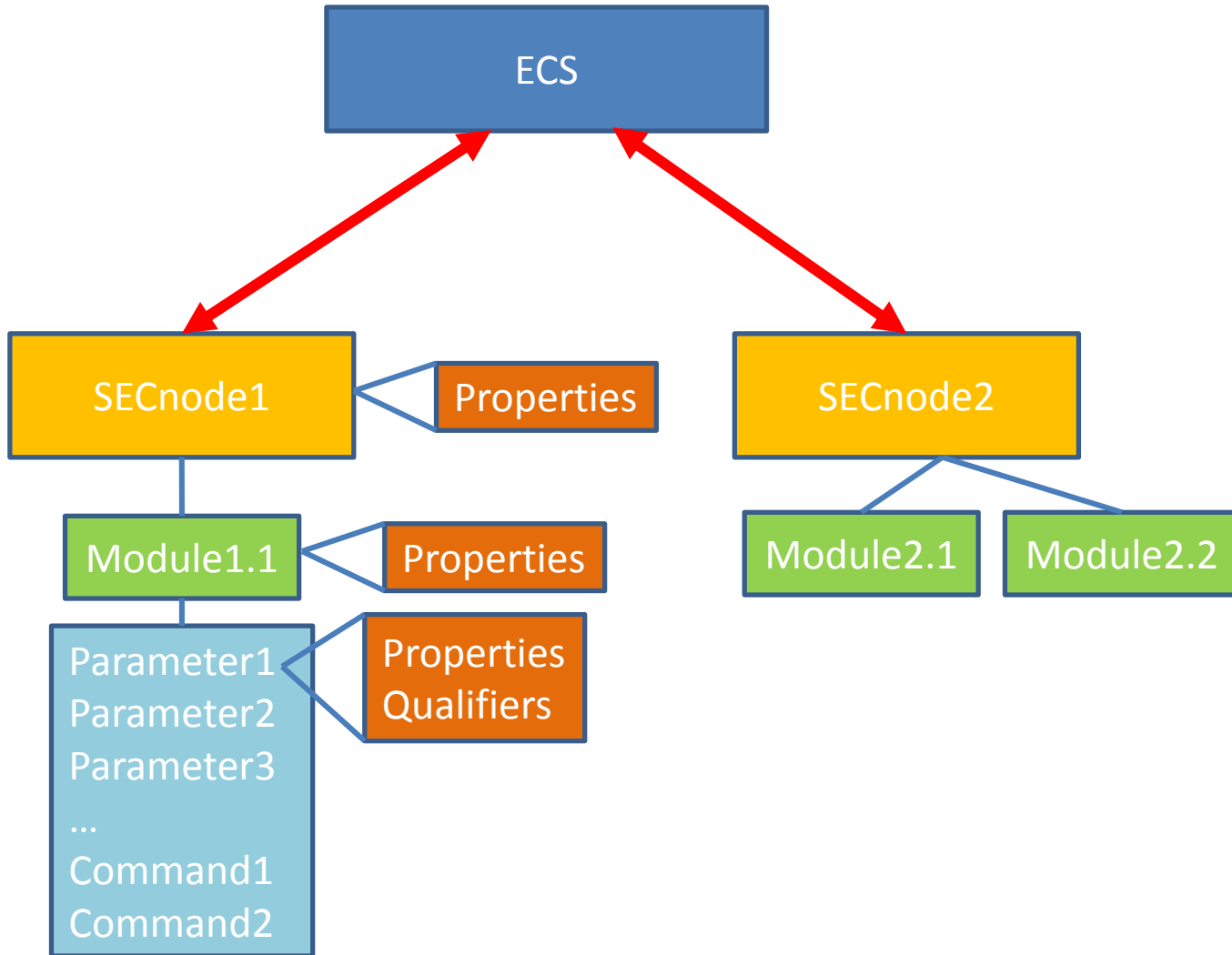
SECoP Basics

- 1) the **philosophy**
- 2) the general **structure** of the SECoP information
- 3) the **syntax** for the SECoP messages
- 4) the set of **rules** for the SECoP logic
- 5) the **meaning** of predefined SECoP components

SECoP Philosophy

- **Self-explaining:** the description of a SEC node must contain all necessary information for a) operating the SEC node by the ECS without further documentation in at least a basic mode, b) providing all relevant metadata information
- **Integrative:** enable the use of SECoP by ECSs with a great variety of design concepts (e.g. synchronous vs. asynchronous communication)
- **Simple:** all parts of SECoP (transport layer, syntax) should be as simple as possible (but as complex as needed)
- **Necessary - sufficient - unambiguous**
- Transport layer: **message oriented** (presently TCP/IP), ASCII
- Protocol is **independent from specific transport layer**
- **Wrap complex functionality** of sample environment equipment on the SEC node side / simplify (standardize) the use of SE equipment by the ECS
- Keep the **overhead** for the SECoP protocol **on SEC node** (server) side **small**
- **Avoid unnecessary traffic**
- Better be **explicit**
- All protocol messages must be **human readable** (with only exception: blob)
- Use **JSON**
- **Impose best-practices to the programmer** of the SEC node by making important features mandatory
- **Must ignore policy**
- Allow for **multiple clients**; if you have more than one client, SECoP does not handle any resulting problems (the SECnode might)
- There should be a **general way of doing things**.

SECoP Structure



SECnode

Module:Parameter
Module:Command

SEC-Node

SE-equipment
e.g. cryostat

Module

Contains all information needed
for one physical parameter
e.g. temperature, mag. field

Parameter

e.g. value, status, target

Command

e.g. go, hold, stop



SEC-Node

SE-equipment
e.g. cryostat

Module

Contains all information needed
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e.g. temperature, mag. field

Parameter

e.g. value, status, target

Command

e.g. go, hold, stop

The screenshot shows the ClientGui interface. On the left, there is a tree view of nodes under '1'. The selected node is 'mod1' under 'HZB-TestNode2'. The tree structure is as follows:

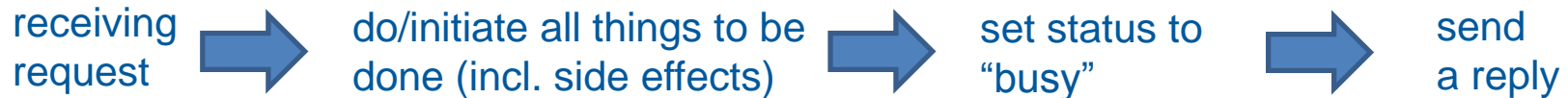
- 1
 - HZB-Testnode1
 - hpd
 - value
 - status
 - target
 - HZB-TestNode2
 - mod1 (selected)
 - value
 - status
 - target
 - ramp
 - useramp
 - _COMMIT
 - go
 - hold
 - stop

On the right, there is a control panel for the selected module 'mod1'. It shows the 'actual Module: mod1' and a list of parameters with their units and control buttons:

Parameter	Module	Unit	Value	Control
value	mod1	K		
target	mod1	K	<input type="text"/>	change
stop			<input type="text"/>	do
status	mod1			
ramp	mod1	K/s	<input type="text"/>	change
useramp	mod1		<input type="text"/>	change
_COMMIT	mod1		<input type="text"/>	change
go			<input type="text"/>	do
hold			<input type="text"/>	do

SECoP rules (handshake)

how is the ECS informed about acceptance of requests:



how is the ECS informed about completion of tasks:



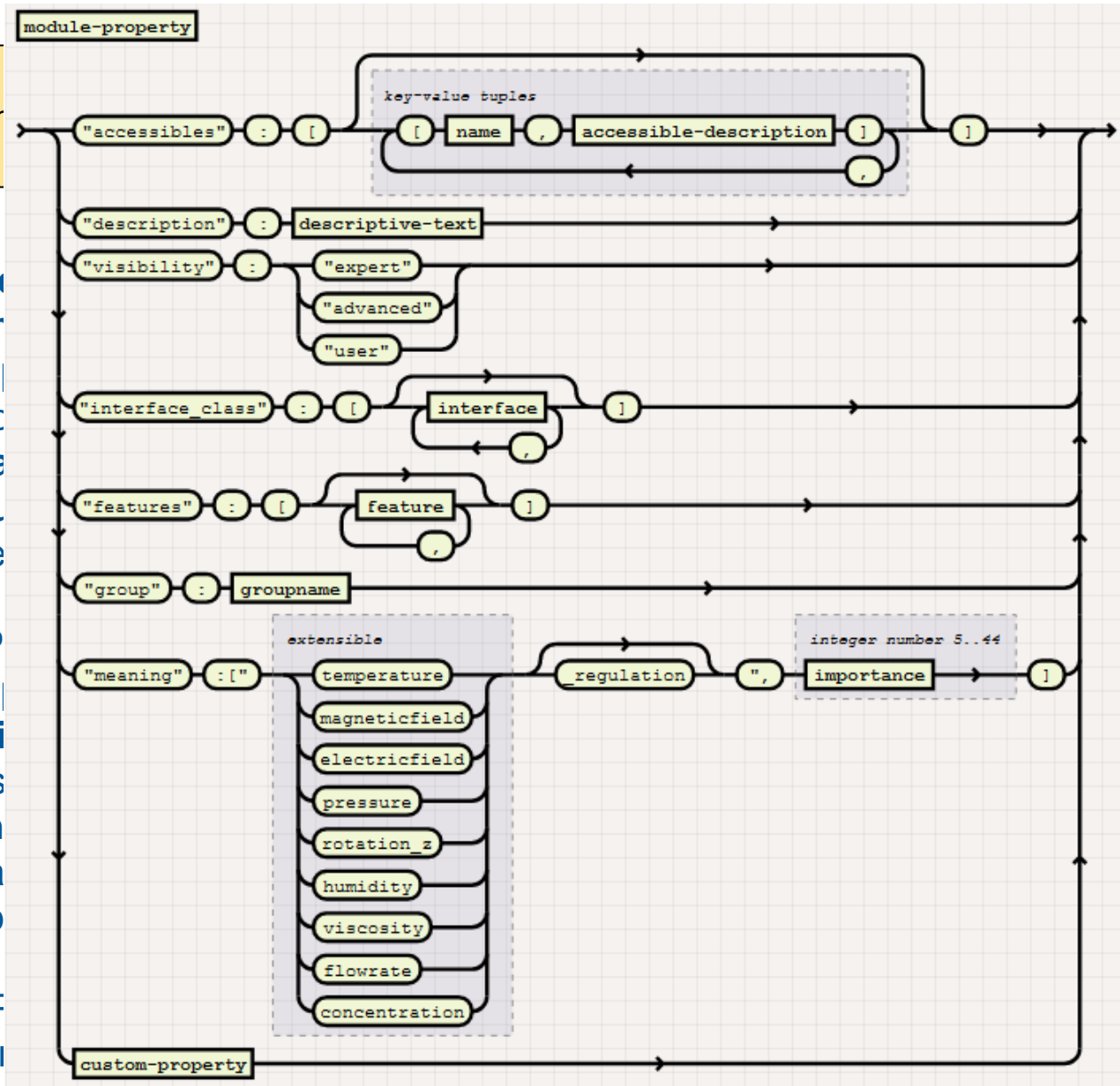
- No message but “change target” and commands may take considerable time. Only these two requests can change the status to busy.
- SEC node may go busy for other reasons (e.g. internal recalibration, other client issuing a command).
- With two or more actions in parallel there is no possibility to differentiate which actions are still running. When all actions are finished: go to “idle”
- SEC node is free to reject any action (but “stop” command). Send an error message if the action is rejected.
- “Stop” command must not be rejected. Stop is ending all running actions.
- SEC node must reject an action (error message send) which can’t be performed immediately (no queueing!) (to be discussed)

SECoP syntax

Definition:
The **static** in
predefined

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 - descrip
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- Module P**
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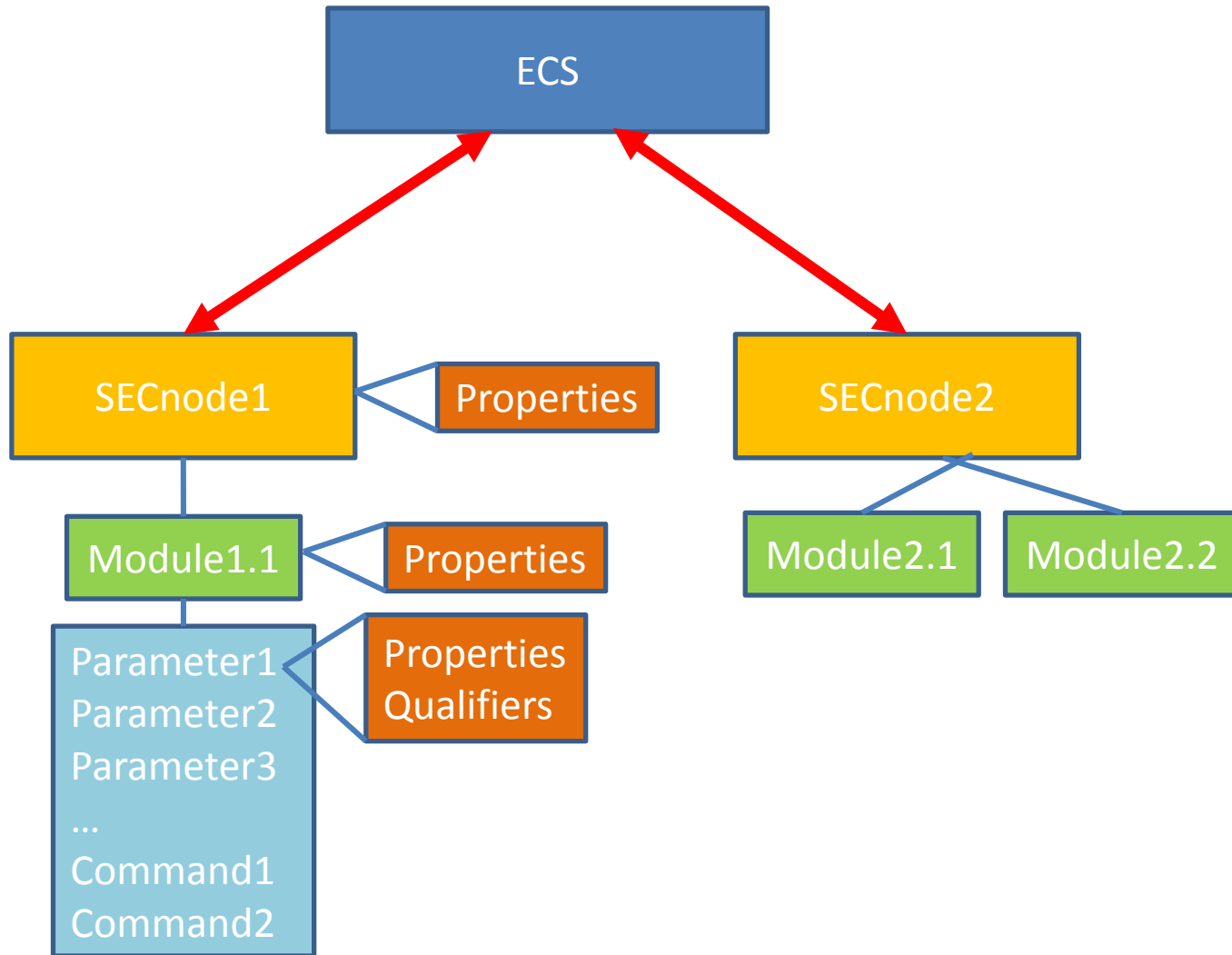
description	request reply	describe describing <i>SEC-node-id description</i>
change value	request reply	change <i>module:parameter value</i> changed <i>module:parameter value</i>
read request	request reply	read <i>module:parameter</i> update <i>module:parameter value</i>

www.github.com/SampleEnvironment/SECoP

SECoP 1.0 Beta

Metadata in SECoP

- **Structure** (module, grouping)
- **Information** (live metadata, static metadata)
- Predefined **meaning** (predefined properties, property „meaning“, interface classes)
- Translation to Nexus



SECnode

Module:Parameter
Module:Command

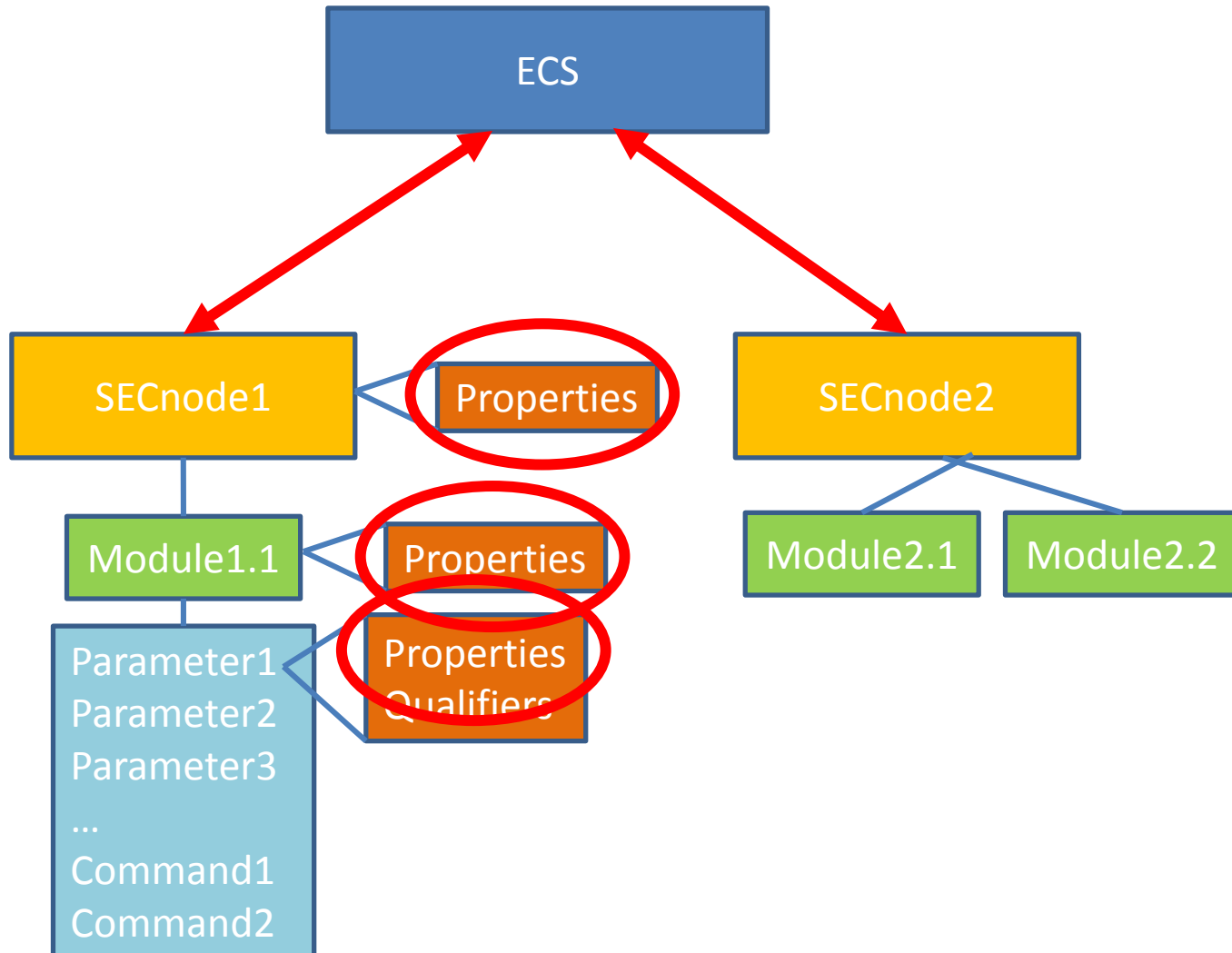
- **Structure** (module, grouping)
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Static Metadata:

must not and cannot change during a running experiment

Basic information: **properties**

- the *equipment_id* and the *description* of a *SEC-node* (both mandatory),
- the *description* (mandatory) and the *meaning* (optional) of a *module*,
- the *description* and the *datatype* of an *accessible* (both mandatory). In general, the *datatype* has a complex structure that can contain among other things the physical unit of a *parameter*.

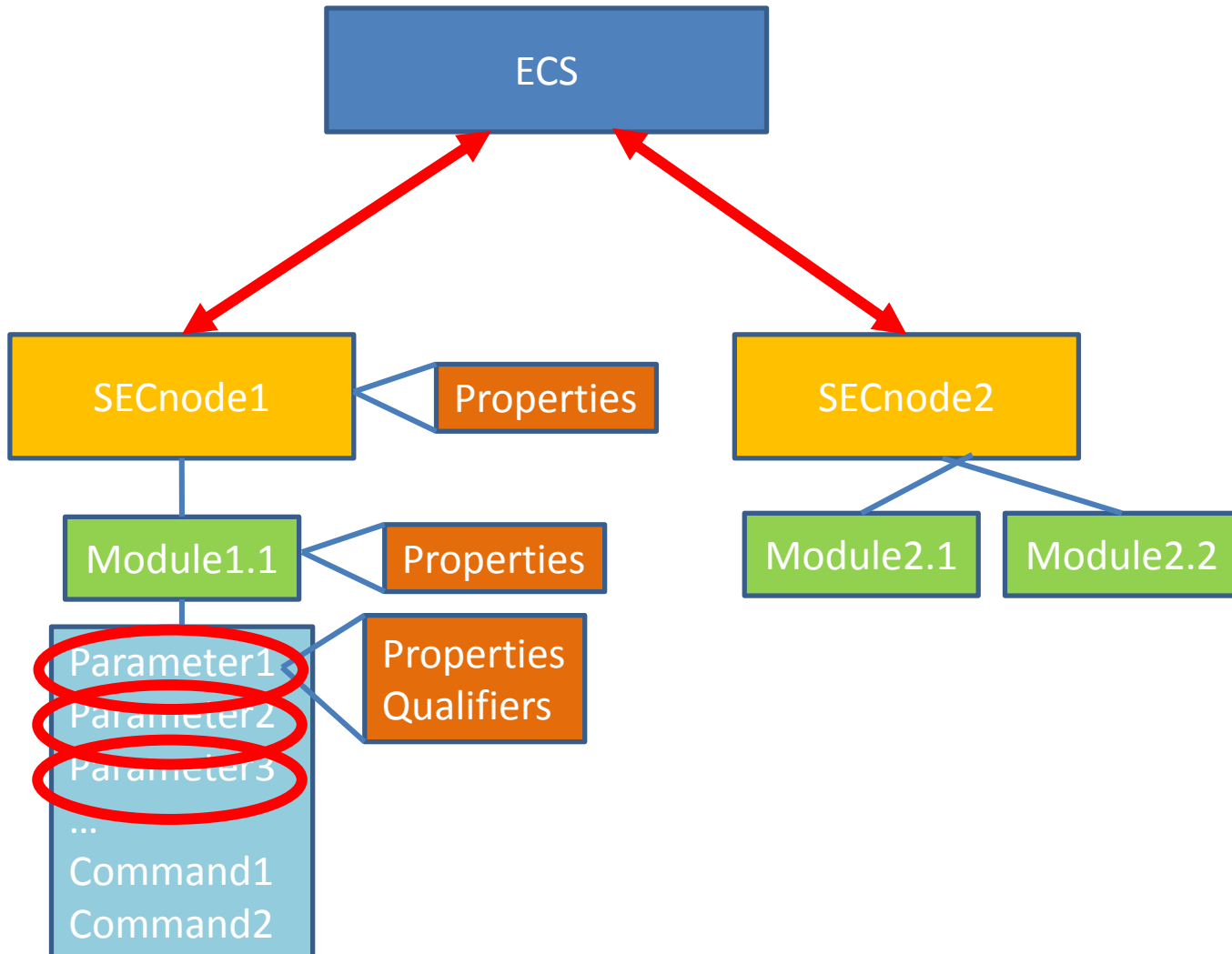


Static Metadata:

must not and cannot change during a running experiment

Numerical and structured metadata: **static parameters**

- Example: Calibration curve of a sensor
- General meaning attributed by interface classes

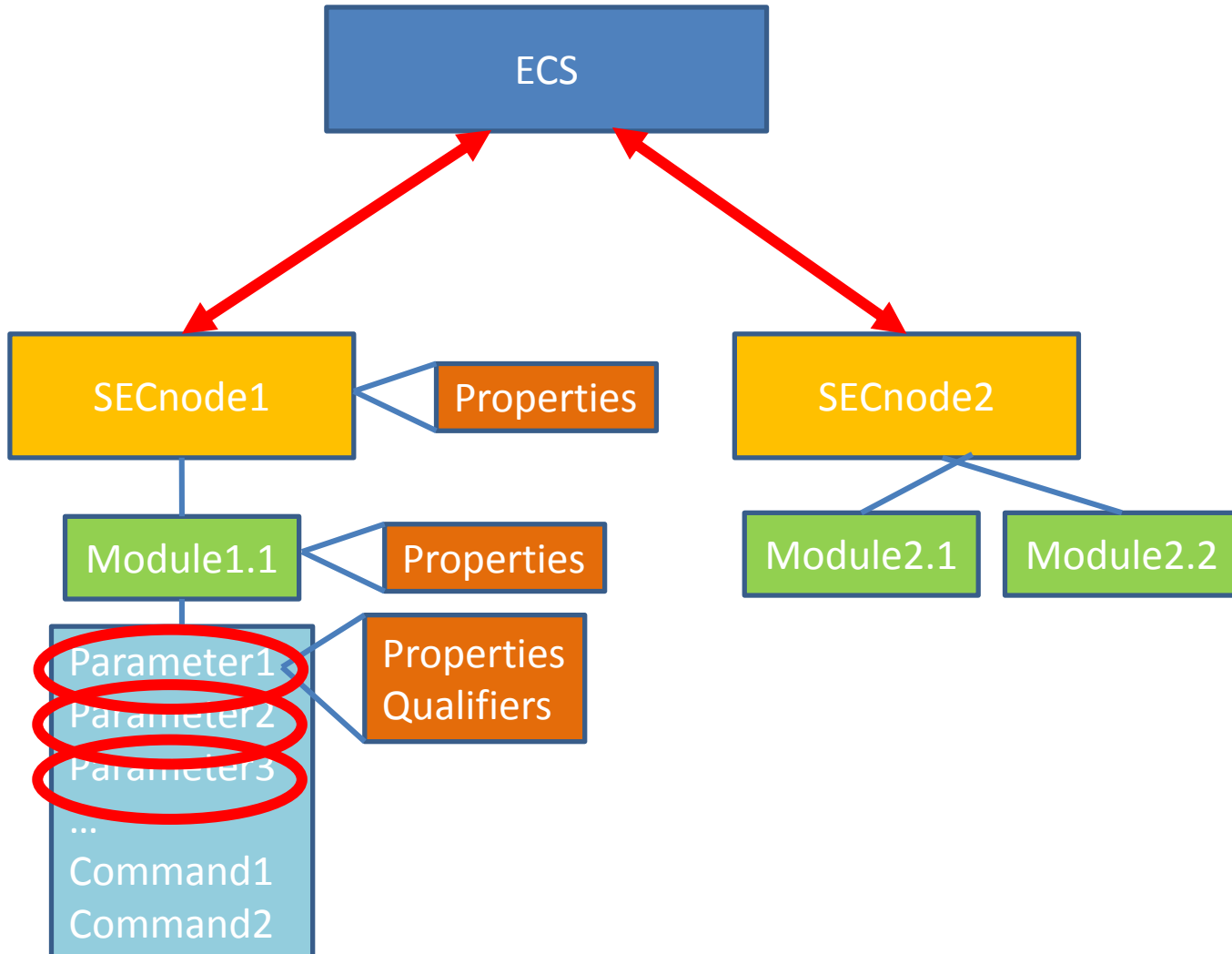


Static parameter: cannot be read
(only describe message)

Live Metadata:

all metadata information that can be altered during the measurement

- (Parameters at sample position (sample temperature, humidity,...))
- Additional information (Helium level, temperature of waterbath (humidity cell):
trasported as SECoP parameters



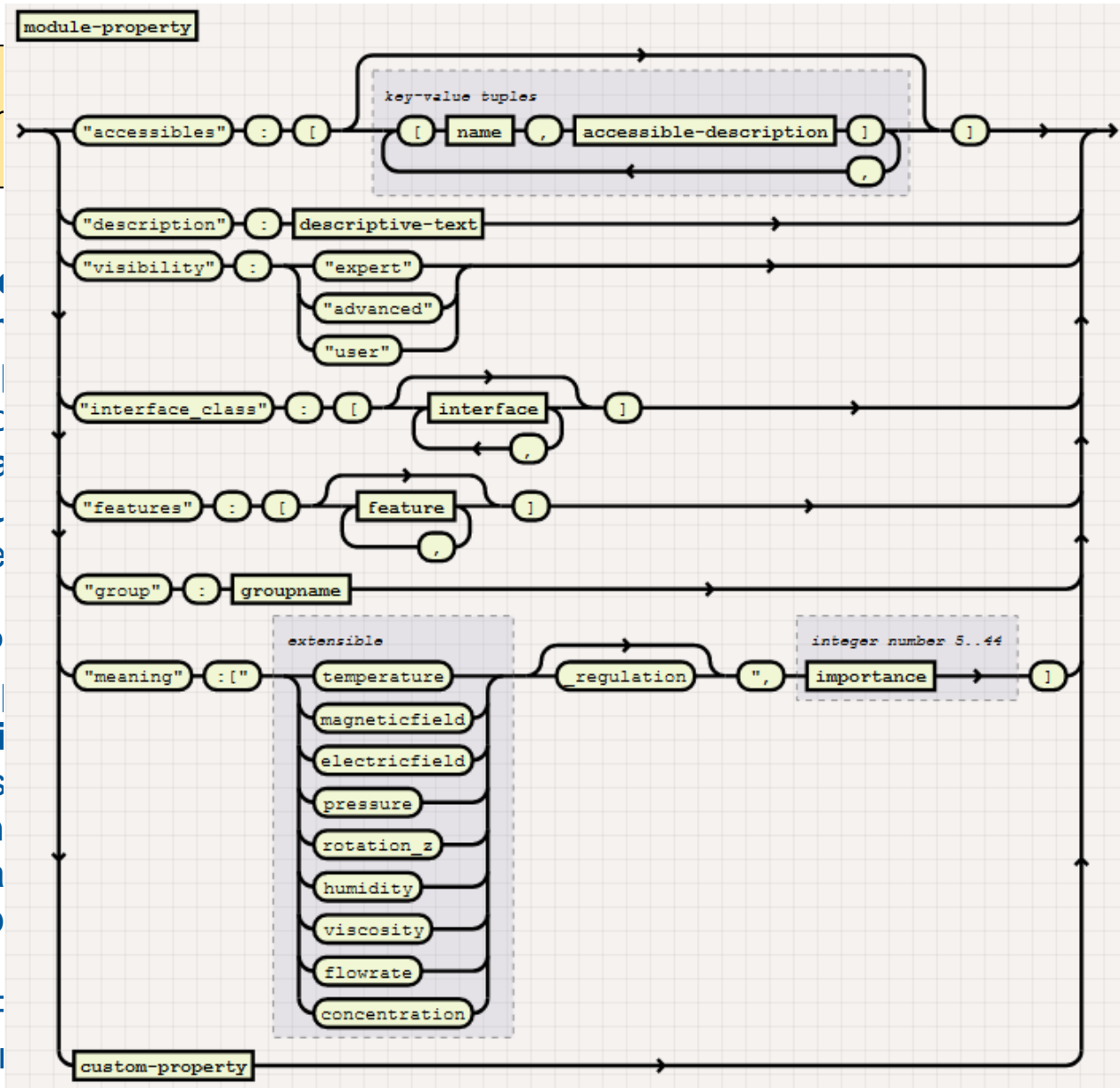
Live parameter: can be read

- **Structure** (module, grouping)
- **Information** (live metadata, static metadata)
- **Predefined meaning** (predefined properties, property „meaning“, interface classes)
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- **Structure** (module, grouping)
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- **Translation to Nexus**

4.1 NXenvironment

The NeXus class NXenvironment is intended for “parameters for controlling external conditions” [2]. In the combination with SECoP, NXenvironment can be best represented by a *SEC-node*.

The fields in NXenvironment can be directly attributed to the SECoP information coming from the *SEC-node*. Table 1 shows a possible mapping scheme.

NeXus (NXenvironment)	SECoP (SEC-node)
name (NXchar)	<i>equipment_id</i>
description (NXchar)	<i>description</i>
program (NXchar)	<i>firmware</i>
(note) (NXnote)	complete answer to “ <i>describe</i> ” message

Table 1: Mapping of NXenvironment

4.2 NXSensor

The NeXus class NXSensor is “used to monitor an external condition. The condition itself is described in NXenvironment.” [2]. Compared to NeXus, SECoP offers here an additional structure level with the possibility to combine several *parameters* in a single *module*. In order to keep all information from both *module* and *parameter*, the entries for NXsensor have to be a combination of *module* and *parameter* information. A possible mapping of the most relevant entries is presented in table 2.

NeXus (NXsensor)	SECoP (<i>parameter</i>)
name (NXchar)	modulename_parametername suggestion: use only “modulename” if <i>parameter</i> is <i>main value</i>
model (NXchar)	<i>description</i> of both the <i>module</i> and <i>parameter</i>
measurement (NXchar)	if <i>main value</i> of a <i>module</i> : map to <i>module</i> property “ <i>meaning</i> ”
value_log (NXlog)	<i>value</i> and timestamp

Table 2: Mapping of NXsensor

Note: The possible keywords for the NeXus measurement are not completely covering all physical sample environment parameters that are typically used in beamline experiments. It would be beneficial to extend this list.

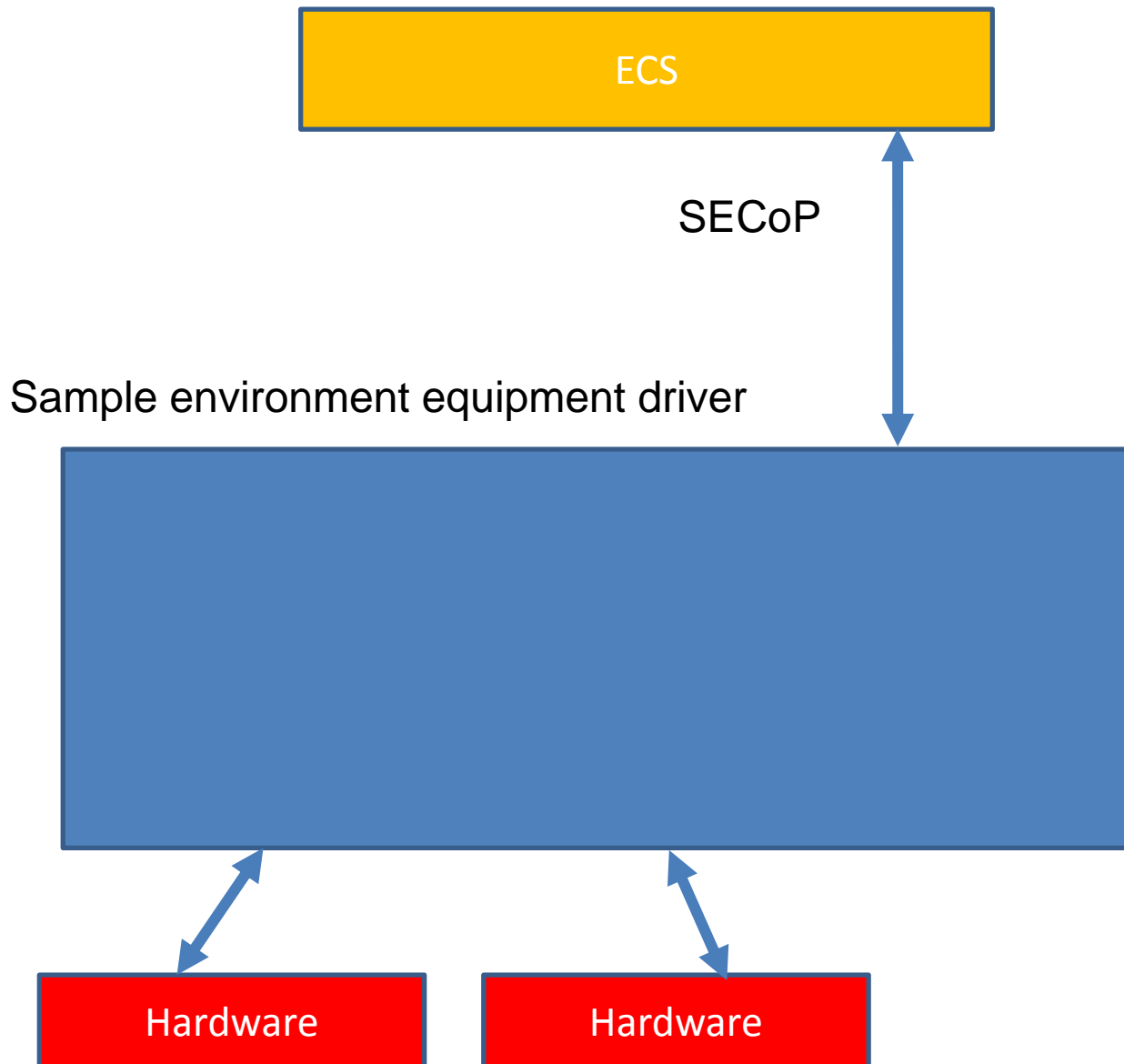
SECoP implementations

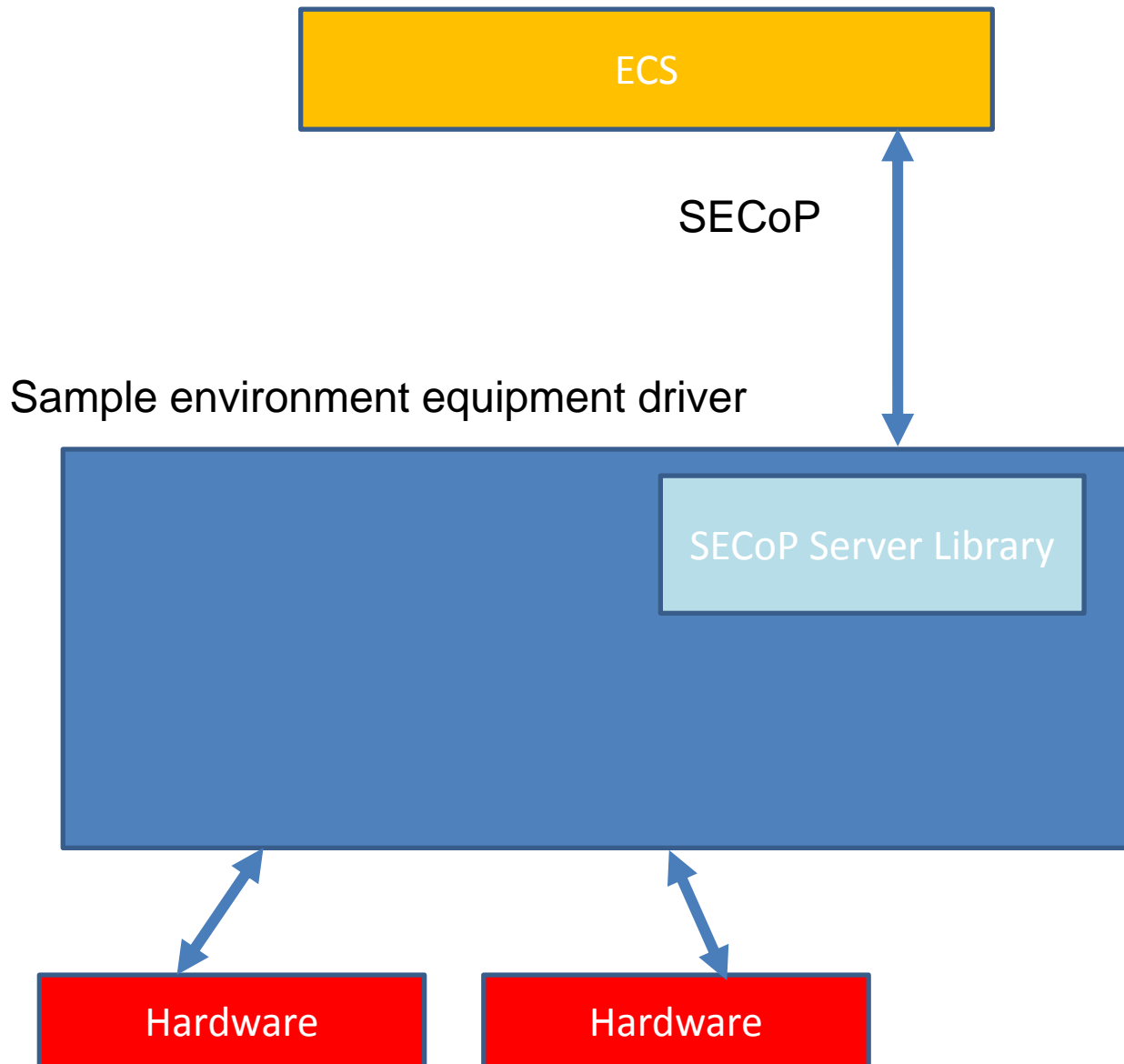
Two solutions, already usable for tests:

- 1) SECoP library** (DLL, c-library) from Frank Wutzler and Lutz Rossa (HZB)
with an API for most compiled languages and an adapter to LabView

- 2) FRAPPY**, a Python framework from Enrico Faulhaber (MLZ), allowing to program a complete SEC node including drivers. Successfully used (in a test setup) for equipment from MLZ to PSI and ILL, and for one smaller lab project at PSI.

a collaborative effort (PSI jumped in – somebody else wants to join?)

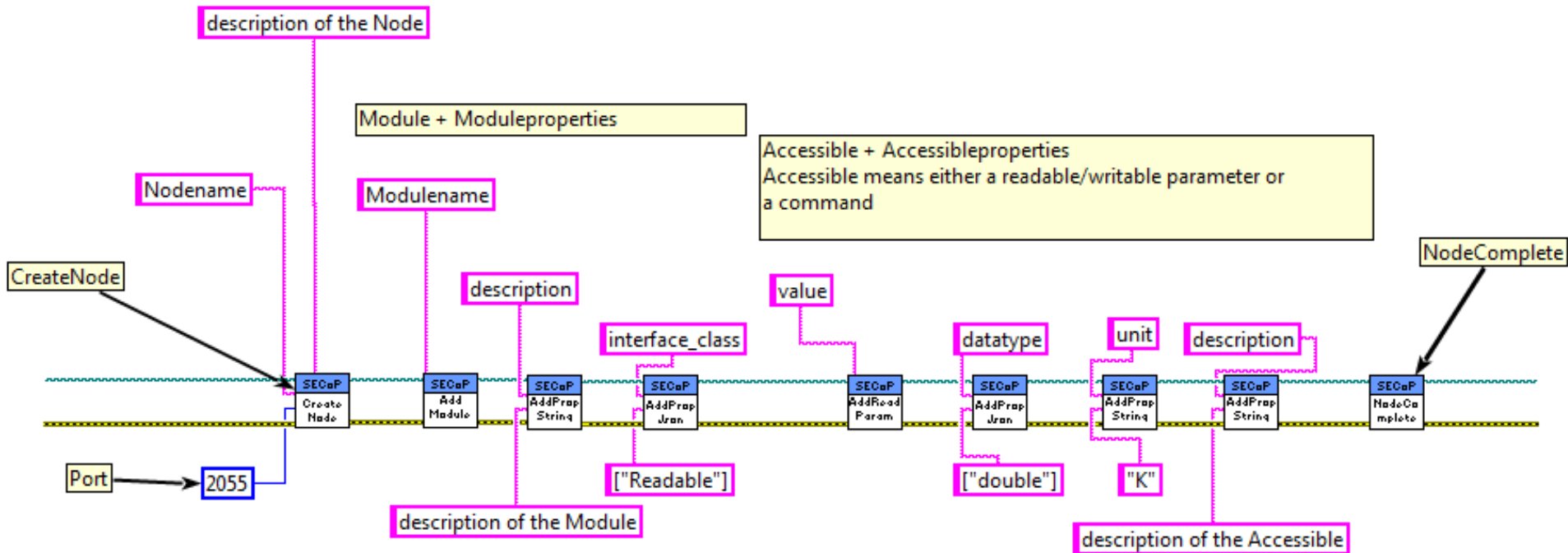




LabVIEW



Creating the SENode



**What still needs
to be done?**

- Finalize next SECoP Version
 - Write documentation / report
-
- Adapt (again) server library for C/C++
 - Finish client library for C/C++
 - Integration in ECS
-
- More tests with real equipment during real experiments
 - Contact to industry
 - Define complex interface classes



SECoP

**simple, inclusive, self explaining
provides metadata**

www.github.com/SampleEnvironment/SECoP



Thank You!



Meeting in Grenoble March 2019

Logo

SECoP